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9. A process for controlling the pressure within a chamber, comprising the steps of:

first generating a pressure sensor signal responsive to the pressure in said chamber;

second generating a step command signal responsive to said pressure sensor signal and a tool logic signal, said step command signal generating comprising applying a pressure control algorithm to said pressure sensor and tool logic signals;

third generating a direction/speed command signal responsive to said step command signal and a valve position feedback signal, said valve position feedback signal comprising data representing the position of a motor drive operatively connected to a valve, said direction/speed command signal generating comprising applying a position control algorithm to said step command and valve position feedback signals;

actuating said valve responsive to said direction/speed command signal, said actuating comprising moving said valve by operation of said motor drive, said actuating resulting in said valve residing in a position, said valve in fluid communication with said chamber:

fourth generating another said valve position feedback signal responsive to said position of said valve, said valve position feedback signal comprising data representing the position of said motor drive operatively connected to said valve; and

repeating said third generating, said actuating and said fourth generating steps until said pressure in controlled adequately.

- 14. A process for controlling the fluid flow through a conduit, comprising the steps of:
- generating a flow sensor signal responsive to the flow in said conduit;
- generating a step command signal responsive to said flow sensor signal and a tool logic
- 4 signal, said step command signal generating comprising applying a flow control algorithm to said
- flow sensor and tool logic signals;

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6	generating a direction/speed command signal responsive to said step command signal and a
7	valve positi n feedback signal, said valve position feedback signal comprising data representing
8	the position of a motor drive operatively connected to a valve, said direction/speed command
9	signal generating comprising applying a position control algorithm to said step command and valve
10	position feedback signals;
11	actuating said valve responsive to said direction/speed command signal, said actuating
12	comprising moving said valve by operation of said motor drive, said actuating resulting in said
13	valve residing in a valve position, said valve in fluid communication with said conduit;
14	generating another said valve position feedback signal responsive to said position of said
15	valve, said valve position feedback signal comprising data representing the position of said motor
16	drive operatively connected to said valve; and
17	repeating said direction/speed command signal generating step, said actuating step and said
18	valve position feedback signal generating step until said fluid flow is controlled adequately.